

26.1. Last time.

Suppose \mathfrak{g} is a semisimple Lie algebra.

(no nonzero solvable ideals)

(\Leftrightarrow every f.d. rep'n is semisimple:
each invariant subspace has a complement)

Find $\mathfrak{h} \subseteq \mathfrak{g}$ an abelian subalgebra acting diagonally via the adjoint representation.

Then decompose $\mathfrak{g} = \mathfrak{h} \oplus \left(\bigoplus_{\alpha} \mathfrak{g}_{\alpha} \right)$

for roots $\alpha \in \mathfrak{h}^*$ s.t. $\text{ad}(H)X = \alpha(H)X$ for
all $H \in \mathfrak{h}$, $X \in \mathfrak{g}_{\alpha}$.

Now if V is some other irrep of \mathfrak{g} , then we can

decompose $V = \bigoplus_{\beta} V_{\beta}$

and we have $\mathfrak{g}_{\alpha+\beta}: V_{\alpha} \rightarrow V_{\alpha+\beta}$.

So - find a highest weight vector

(according to some semi-arbitrary choice of positive roots)

- Push it around via elements in \mathfrak{g} .

- Get the entire irrep this way.

- So you can classify by their highest weight vectors.

[Recall the Killing form

$$B(X, Y) = \text{Tr}(\text{ad } X \text{ ad } Y) : \mathfrak{g} \rightarrow \mathfrak{g}$$

Review bottom of 25.6

26.4. (Note: 26.2 ~ 25.7, 26.5 ~ 23.10)

Let's up the ante.

* For a given semisimple \mathfrak{g} , classify all representations.

Let's classify semisimple Lie algebras while we're at it!

The root system ~~class~~ determines the Lie algebra (probably this is not obvious) so we'll classify those.

Properties.

The roots R of \mathfrak{g} span a real subspace of \mathfrak{h}^* on which the Killing form is positive definite.

Call the space \mathbb{E} and the Killing form $(-, -)$.

- (1) R is finite and spans \mathbb{E} .
- (2) $\alpha \in R \iff -\alpha \in R$, and $k\alpha \notin R$ for any $k \neq \pm 1$.
- (3) For $\alpha \in R$, the reflection W_α in the hyperplane α^\perp mops R to itself.
- (4) If $\alpha, \beta \in R$, the number
$$n_{\beta\alpha} = 2 \frac{(\beta, \alpha)}{(\alpha, \alpha)}$$
 is an integer.

We saw (3), (4) before and (1) is true by construction.

Why is (2) true?

Consider the representation $\mathfrak{i} = \bigoplus \mathfrak{g}_\alpha$ of $\mathfrak{sl}_2 \cong \mathfrak{g}$.

Let α be the smallest nonzero root in the string.

Recall we could find subalgebras iso. to \mathfrak{sl}_2 acting on any chain of roots.

But can decompose $\mathfrak{i} = \mathfrak{sl}_2 \oplus \mathfrak{i}'$.

\mathfrak{i}'
no eigenvalue
1 or 2'

So must be trivial.

Property (4'). Let θ be the angle between α and β .

$$n_{\beta\alpha} = 2 \cos(\theta) \frac{\|\beta\|}{\|\alpha\|} \in \mathbb{Z}$$

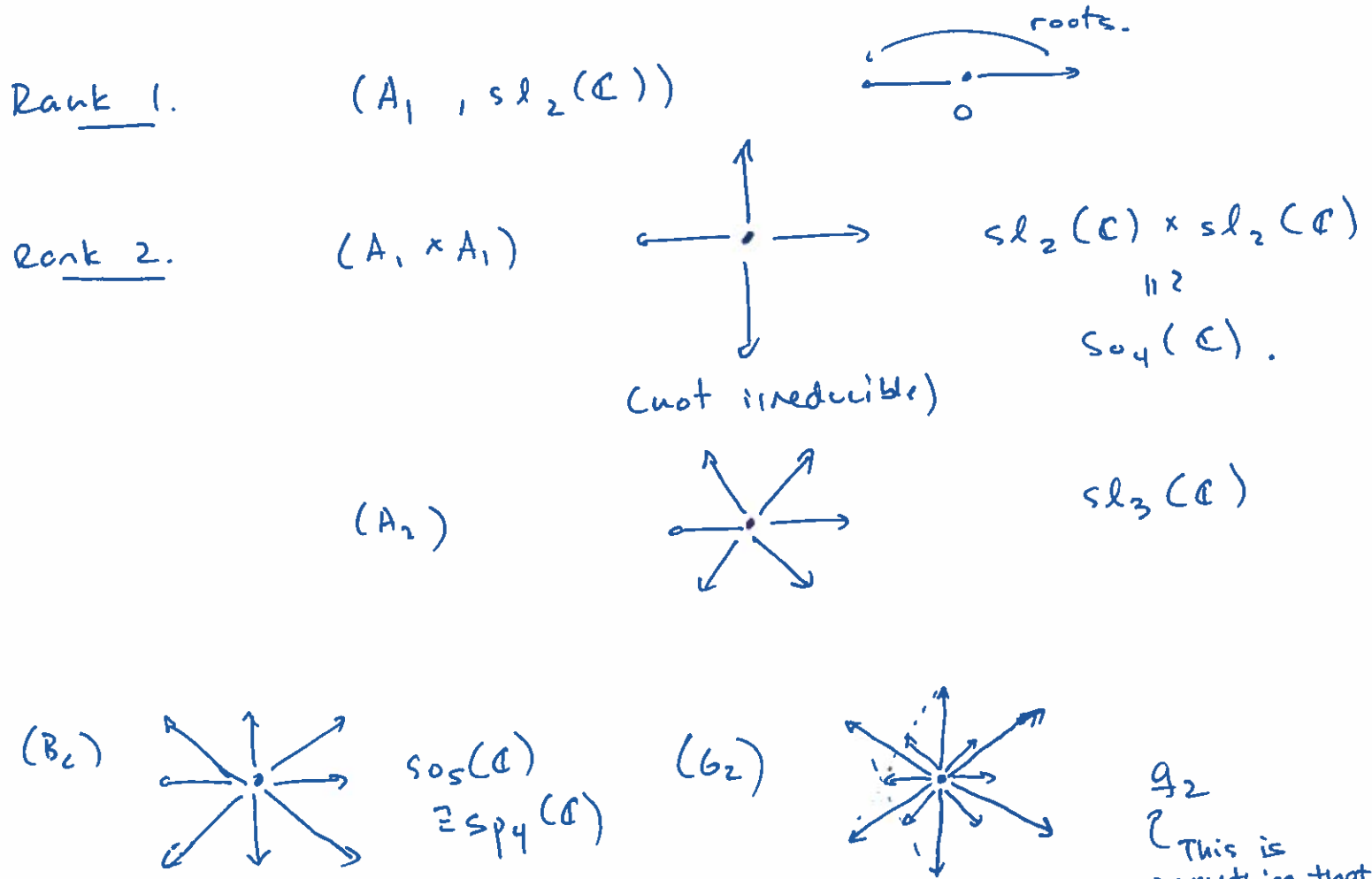
$$n_{\alpha\beta} = 2 \cos(\theta) \frac{\|\alpha\|}{\|\beta\|} \in \mathbb{Z} \implies \text{so } \underline{4 \cos(\theta) \in \mathbb{Z}}$$

This means $\theta \in \left\{ \frac{\pi}{6}, \frac{\pi}{4}, \frac{\pi}{3}, \frac{\pi}{2}, \frac{2\pi}{3}, \frac{3\pi}{4}, \frac{5\pi}{6} \right\}$.

The only angles whose cosines you actually know.

Write $n = \dim_{\mathbb{R}} \mathfrak{E} = \dim_{\mathbb{C}} \mathfrak{h}$, the rank of the Lie algebra.

What can we get?



26.6 .

Some more properties.

(5) If α, β are roots with $\beta \neq \pm \alpha$, then the α -string through β

$$\beta - p\alpha, \dots, \beta - \alpha, \beta, \beta + \alpha, \dots, \beta + q\alpha$$

has at most four in a row so $p+q \leq 3$. Also $p-q \equiv n_{\beta\alpha}$.

Why? Use the Weyl group. Reflect across the α axis.

The reflection w_α flips the string, so

$$w_\alpha(\beta + q\alpha) = \cancel{w_\alpha(\beta - q\alpha)} = \beta - p\alpha$$

$$\text{but also } w_\alpha(\beta + q\alpha) = (\beta - n_{\beta\alpha}\alpha) - q\alpha$$

$$\text{so } p = q + n_{\beta\alpha}.$$

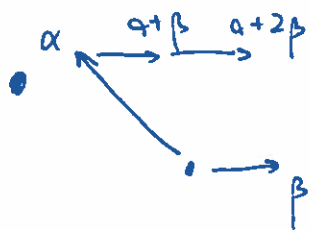
To get $p+q \leq 3$, take $p=0$; $q = -n_{\beta\alpha} \leq 3$.

(6) If α, β roots with $\beta \neq \pm \alpha$, then:

$$(\beta, \alpha) > 0 \implies \alpha - \beta \text{ is a root}$$

$$(\beta, \alpha) < 0 \implies \alpha + \beta \text{ is a root}$$

$$(\beta, \alpha) = 0 \implies \alpha - \beta, \alpha + \beta \text{ are both roots or both nonroots.}$$



26.7

Call a root simple if it is positive and not the sum of two other positive roots.

(7) If α and β are distinct simple roots, then $\alpha - \beta$ and $\beta - \alpha$ are not roots.
(Immediate)

(8) The angle between two distinct simple roots cannot be acute. (Follows from (6), (7).)

(9) The simple roots are linearly independent.

Exercise. If a set of vectors lies on one side of a hyperplane, and all angles are at least 90° , the vectors are LI.

(10) There are precisely n simple roots.
(Immediate)

(11) Every positive root can be written uniquely as a nonnegative integral linear combination of simple roots.

(Uniqueness from 9)

(Existence: if it weren't, get another simple root).

To any root system associate a Dynkin diagram:

Circles $\xrightarrow{\text{simple}}$ roots.

Connect if the angle between them $> \frac{\pi}{2}$.

$\circ \text{---} \circ \quad \frac{2\pi}{3}$

(roots will be of equal length)

$\circ \text{====} \circ \quad \frac{3\pi}{4}$

(from longer to shorter)

$\circ \text{=====} \circ \quad \frac{5\pi}{6}$

26.8.

Examples.

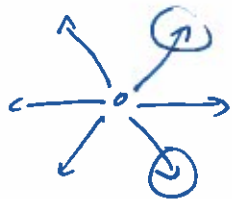
$A_1 : \mathfrak{sl}_2(\mathbb{C})$



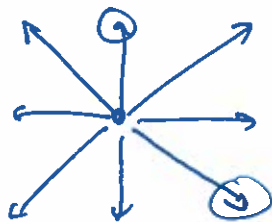
Dynkin



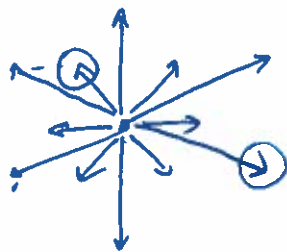
$A_2 : \mathfrak{sl}_3(\mathbb{C})$



$B_2 : \mathfrak{so}_5 \cong \mathfrak{sp}_4$



$G_2 :$



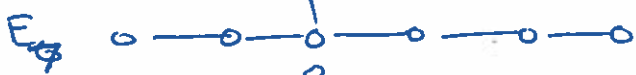
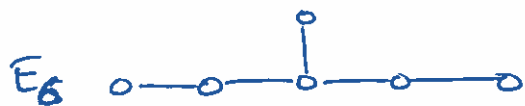
Theorem: This is all possible Dynkin diagrams:

$A_n \quad (\mathfrak{sl}_{n+1}(\mathbb{C})) \quad \circ - \circ - \dots - \circ - \circ \quad (n \geq 1)$

$B_n \quad (\mathfrak{so}_{2n+1}(\mathbb{C})) \quad \circ - \circ - \dots - \circ \Rightarrow \circ \quad (n \geq 2)$

$C_n \quad (\mathfrak{sp}_{2n}(\mathbb{C})) \quad \circ - \circ - \dots - \circ \Leftarrow \circ \quad (n \geq 3)$

$D_n \quad (\mathfrak{so}_{2n}(\mathbb{C})) \quad \circ - \circ - \dots - \circ \begin{cases} \circ \\ \circ \end{cases} \quad (n \geq 4)$



1.

Last Lie Groups class.

(1) Review what we've done.

(2) A loose end. How to reverse engineer the classification?

(3) A little bit about PHV's and my interests.

(4) Teaching evaluations.

Review:

Ch. 1 Introduced matrix Lie groups: closed subgps of $GL_n(\mathbb{C})$.

Examples. GL_n , SL_n , $U_n(\mathbb{C})$, $O_n(\mathbb{R})$ and $SO_n(\mathbb{R})$

And SU_n

Also Sp_n .

Properties they might enjoy:

compactness

(path) connectedness

simple connectedness.

Proved $GL_n(\mathbb{C})$ is connected. Use Jordan form!

Lie groups in general: smooth manifolds G with a group structure;

$$G \times G \xrightarrow{\text{product}} G$$

$$G \xrightarrow{\text{inv.}} G$$

one smooth maps.

Ch. 2. The matrix exponential.

Analysis for matrices!

Defined $\exp: M_n(\mathbb{C}) \rightarrow M_n(\mathbb{C})$ abs convergent

$$\text{Recall } \|X\| = \left(\sum_{j,k} |x_{j,k}|^2 \right)^{1/2} = (\text{tr } X^* X)^{1/2}$$

$$\text{which satisfies } \|X + Y\| \leq \|X\| + \|Y\|$$

$$\|XY\| \leq \|X\| \cdot \|Y\|.$$

Studied this analytically,

$$\frac{d}{dt} e^{tX} = X e^{tX} = e^{tX} X.$$

2.

Remember that e^{X+Y} is not always $e^X e^Y$

It is if X and Y commute.

When X and Y don't commute, we have
Baker - Campbell - Hausdorff.

One way to compute: If $X = CDC^{-1}$
then $e^X = C e^D C^{-1}$.

If D is diagonal, e^D is very easy to compute

(If D is upper triangular, it's not so bad.)

So this can be used to compute e^X in practice.

There is also a matrix logarithm, again defined by
power series.

But in general it only converges when $\|A - I\| < 1$.

So we have locally inverse bijections

$$\begin{array}{ccc}
 M_n(\mathbb{C}) & \xrightleftharpoons[\log]{\exp} & M_n(\mathbb{C}) \\
 \uparrow & & \uparrow \\
 0 & & I \\
 \hline
 & & \\
 \|X\| < \log 2 & & \|A - I\| < 1 \\
 \Rightarrow \log e^X = X & & \Rightarrow e^{\log A} = A.
 \end{array}$$

Lie Product Formula
$$e^{X+Y} = \lim_{n \rightarrow \infty} \left(e^{\frac{X}{n}} e^{\frac{Y}{n}} \right)^n$$

Not exciting, but useful in proofs.

3.

One parameter subgroups:

Any function $A: \mathbb{R} \rightarrow GL_n(\mathbb{C})$ which is

(1) continuous, (2) $A(0) = I$, (3) a homomorphism
(i.e. $A(t+s) = A(t)A(s)$)

Thm. All are of the form e^{tX} for some X .

Ch. 3. Lie algebras.

Introduced axiomatically (vector space with $[\cdot, \cdot]$
satisfying bilinearity, skew symmetry,
Jacobi)

Used example. Any associative algebra with $[X, Y] = XY - YX$.

(There's a whole classification theory.)

Defined homomorphisms, ad_X , irreducible (no ideals)
simple (irred, dim ≥ 2)
etc.

If G is a matrix Lie group, its Lie algebra is

$$\mathfrak{g} = \left\{ X : e^{tX} \in G \text{ for all } t \in \mathbb{R} \right\}.$$

Check: You really do get a Lie algebra.

Also if G is commutative, so is \mathfrak{g} (i.e. bracket $\equiv 0$)

Computations:

$$\mathfrak{gl}(n) = \text{Mat}_n \text{ (or just } M_n)$$

$$\mathfrak{sl}(n) = \{ X \in M_n : \text{tr}(X) = 0 \}.$$

$$\mathfrak{u}(n) = \{ X \in M_n(\mathbb{C}) : X^* = -X \}$$

$$\mathfrak{o}(n) = \{ X \in M_n(\mathbb{R}) : X^T = -X \}.$$

4.

Thm. Lie group homomorphisms induce Lie alg. homomorphisms.

Given $\Phi: G \rightarrow H$, there exists $\phi: \mathfrak{g} \rightarrow \mathfrak{h}$
defined by
$$\phi(X) = \left. \frac{d}{dt} \Phi(e^{tX}) \right|_{t=0}$$

and satisfying
$$\Phi(e^X) = e^{\phi(X)}.$$

i.e.

$$\begin{array}{ccc} G & \xrightarrow{\Phi} & H \\ \exp \uparrow & \circlearrowleft & \uparrow \exp \\ \mathfrak{g} & \xrightarrow{\phi} & \mathfrak{h} \end{array}$$

Defined a map
$$Ad_A: \mathfrak{g} \rightarrow \mathfrak{g}$$

$$X \rightarrow AXA^{-1}$$

(You do get an element of \mathfrak{g} .)

The map $A \rightarrow Ad_A$ is a Lie group homomorphism $G \rightarrow GL(\mathfrak{g})$, and its associated Lie algebra hom $\mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g})$ is ad_{\bullet} ($X \rightarrow ad_X := Y \rightarrow [X, Y]$),

Thm 3.42. We have mutually inverse ^{local} homeomorphisms

$$\mathfrak{g} \begin{array}{c} \xrightarrow{\exp} \\ \xleftarrow{\log} \end{array} G.$$

Did this for all matrices already. Point is that the images land in G and \mathfrak{g} respectively.

5.

One consequence. \mathfrak{g} is the tangent space to the identity to G , i.e.

$$X \in \mathfrak{g} \longmapsto \left\{ \begin{array}{l} \exists \text{ smooth curve } \gamma: \mathbb{R} \rightarrow M_n(\mathbb{C}) \\ \gamma(0) = I \\ \text{and } \left. \frac{d\gamma}{dt} \right|_{t=0} = X \end{array} \right\}.$$

Another. If G is a connected matrix Lie group, every elt. $A \in G$ can be written

$$A = e^{X_1} e^{X_2} \dots e^{X_m} \quad \text{for } X_1, \dots, X_m \in \mathfrak{g}.$$

Another. If two Lie group laws induce the same Lie alg. hom, they're the same.

Ch. 4. Representation Theory.

Interested in (f.d., cpx) reps $\Pi: G \rightarrow GL(V)$

$$\pi: \mathfrak{g} \rightarrow \mathfrak{gl}(V)$$

(Recall Π induces π)

~~Exam~~ Looked at various examples.

One: $\mathbb{C} \times SU(2)$ or $GL(2)$
or $SU(2)$ acting on

$$\underline{\text{Sym}^m(2)}$$

homog polys of degree m
in 2 cpx vars.

Several ways to define (all isomorphic)

$$(\Pi_m(U)f)(z) = f(U^{-1}z) \quad \text{for } f \in \text{Sym}^m(2)$$

$$U \in GL(2).$$

Usually you just see

$$U \circ f(z) = f(U^{-1}z).$$

6. We computed the associated Lie algebra rep'n.

Saw the usual pattern.

$$H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad X = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad Y = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

Then under the Lie algebra rep'n, $\begin{pmatrix} z_1^{m-k} & z_2^k \end{pmatrix}$ is an eigenvector for H with eigenvalue $-m + 2k$.

X and Y shift the exponent up/down by one.

* These rep'n's are all irreducible

* They are all the irred reps of $\mathfrak{sl}(2)$.

* Hence they describe the rep th'y of $SL(2)$.

ch. 5.

BCH and its consequences.

BCH theorem. If X, Y are in $M_n(\mathbb{C})$ with $\|X\|, \|Y\|$ small

then
$$\log(e^X e^Y) = X + \int_0^1 g(e^{\text{ad}_X} e^{t \text{ad}_Y})(Y) dt$$

$$= X + Y + \frac{1}{2} [X, Y] + \frac{1}{12} [X, [X, Y]]$$

$$- \frac{1}{12} [Y, [X, Y]] + \dots$$

The point is that it is described entirely in terms of the Lie bracket.

7.

Consequences:

* Given $G, H, \mathfrak{g}, \mathfrak{h}$, $\phi: \mathfrak{g} \rightarrow \mathfrak{h}$.

If G is simply connected, then ϕ determines a unique hom $\Phi: G \rightarrow H$ with $\Phi(e^X) = e^{\phi(X)}$ for $X \in \mathfrak{g}$.

Cor. If G, H simply connected and $\mathfrak{g} \cong \mathfrak{h}$, then $G \cong H$.

Construct a local isomorphism and extend.

(In general: given G, H with G simply con'd, a local homomorphism $G \rightarrow H$ extends uniquely to a global one.)

If G is not simply connected you can consider its universal cover \tilde{G} and get $\tilde{\Phi}: \tilde{G} \rightarrow H$.

\tilde{G} and G will have the same Lie algebra.

* Given $G, \mathfrak{g}, \mathfrak{h} \in \mathfrak{g}$. There is a unique connected Lie subgroup H of G with Lie alg. \mathfrak{h} .
(These aren't necessarily closed.)

* Theorem. If \mathfrak{g} is any f.d. real Lie algebra, there is a connected Lie subgroup G of $GL(n, \mathbb{C})$ whose Lie alg. is iso to \mathfrak{g} .