

11.1 .

W. Rossmann, Lie Groups (basically the same)

Just working with matrices (no Lie groups or algebras yet)

$$\text{Ad}(A) Y = A Y A^{-1}.$$

$$\text{ad}(X) Y = X Y - Y X.$$

Proposition. $\text{Ad}(\exp X) = \exp(\text{ad } X).$

What does $\exp(\text{ad } X)$ mean?

It can only mean one thing: $1 + \text{ad } X + \frac{(\text{ad } X)^2}{2} + \frac{(\text{ad } X)^3}{6} + \dots$

Both sides are operations on matrices, so the claim is, for all matrices Y of the same size,

$$\text{Ad}(\exp X) Y = \exp(\text{ad } X) Y$$

e.g.

$$\begin{aligned} (\exp X) Y (\exp X)^{-1} &= Y + [X, Y] + \frac{1}{2} [X, [X, Y]] \\ &\quad + \frac{1}{6} [X, [X, [X, Y]]] \\ &\quad + \dots \end{aligned}$$

$$= \sum_{k=0}^{\infty} \frac{1}{k!} (\text{ad } X)^k Y.$$

Proof. Let $A(t) = \text{Ad}(\exp tX).$

11.2

$$\text{Then } A'(t) Y = \frac{d}{dt} (\exp(tX) Y \exp(-tX))$$

$$= X \exp(tX) Y \exp(-tX) + \exp(tX) Y \exp(-tX) \cdot (-X)$$

$$= \text{ad}(X) \text{Ad}(\exp(tX)) Y.$$

} Store at this for 15 seconds until you understand why it's a tautology!

$$= \text{ad}(X) \cdot A(t) Y$$

Also $A(0) = I$ (as an operation on matrices, so an element of $GL(n^2)$ if we were starting with $n \times n$ matrices).

By what we have seen, the unique solution to this differential equation is $A(t) = \exp(t \text{ad } X)$.

This (with $t=1$) is what we wanted!

Back to Hall, the machinery was set up as:

$$G \xrightarrow{\Phi} H \quad \text{Lie group hom}$$

$$\mathfrak{g} \xrightarrow{\phi} \mathfrak{h} \quad \text{defined w/ } \Phi(e^X) = e^{\phi(X)}$$

Indeed, get $\Phi(e^{tX}) = e^{tZ}$ simul. for all $t \in \mathbb{R}$

(classification of 1PS's)

11.3

$$\text{We had } \text{Ad}_A : \mathfrak{g} \rightarrow \mathfrak{g} \\ (\text{or } \text{Ad}(A)) \quad X \rightarrow A X A^{-1}$$

and $\text{Ad}_A \text{Ad}_B = \text{Ad}_{AB}$ so this is a rep'n
 $G \rightarrow \text{GL}(\mathfrak{g})$.

$$\text{also had } \text{ad}_A : \mathfrak{g} \rightarrow \mathfrak{g} \\ Y \rightarrow [A, Y] = AY - YA.$$

This is a map $\mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g})$ (not $\text{GL}(\mathfrak{g})$)

Let us call by " ϕ " the Lie algebra map induced by
 $\text{Ad} : G \rightarrow \text{GL}(\mathfrak{g})$. It will be a map $\mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g})$.

How to define? Will have

$$\text{Ad}(e^{+X}) = e^{+Z} \text{ for some } Z \in \mathfrak{gl}(\mathfrak{g}) \\ (\text{this is } \phi(X))$$

and (see again Thm 3.2e) it can be computed by

$$\begin{aligned} \phi(X) &= \left. \frac{d}{dt} \text{Ad}(e^{+X}) \right|_{t=0} \\ &= \left. \frac{d}{dt} \left\{ Y \rightarrow \frac{d}{dt} e^{+X} Y e^{-+X} \right\} \right|_{t=0} \\ &= \left\{ Y \rightarrow \left. \frac{d}{dt} e^{+X} Y e^{-+X} \right|_{t=0} \right\} \\ &= \left\{ Y \rightarrow \left(X e^{+X} Y e^{-+X} + e^{+X} Y e^{-+X} \cdot (-X) \right) \Big|_{t=0} \right\} \\ &= \left\{ Y \rightarrow XY - YX \right\} = \text{ad}(X). \end{aligned}$$

which is what we damn well expected.

11.4

The exponential map.

Def. If G is a matrix Lie group, w/ Lie alg. \mathfrak{g} , the exponential map for G is the map

$$\exp: \mathfrak{g} \longrightarrow G.$$

We already know this is well-defined.

Thm. (true, but we didn't prove it) Every matrix in $GL_n(\mathbb{C})$ is e^X for some $X \in M_n(\mathbb{C})$.

But be careful.

Example. Let $A = \begin{pmatrix} -1 & 1 \\ 0 & -1 \end{pmatrix} \in SL_2(\mathbb{C})$.

There does not exist $X \in \mathfrak{sl}_2(\mathbb{C})$ with $e^X = \begin{pmatrix} -1 & 1 \\ 0 & -1 \end{pmatrix}$.

Proof. If such X existed, if it were diagonalizable then A would be too.

So X has a repeated eigenvalue which must be 0 (\mathfrak{sl}_2 : trace 0).

So $Xv = 0$ for some $v \rightarrow e^X v = v$

So e^X has 1 as an EV.

But the above matrix does not.

So annoyances:

The exponential map may not be onto

It may not be one-to-one

but it is locally surj.

11.5

Thm [3.42]. For each $0 < \epsilon < \log 2$, ~~write~~ write

$$U_\epsilon = \{X \in M_n(\mathbb{C}) : \|X\| < \epsilon\}$$

$$V_\epsilon = \exp(U_\epsilon)$$

Let $G \in GL_n(\mathbb{C})$ matrix Lie group w/ Lie alg. \mathfrak{g}

Then: there exists $\epsilon \in (0, \log 2)$ s.t. for $A \in V_\epsilon$,

$$A \in G \iff \log A \in \mathfrak{g}.$$

What we've proved before: (Theorem 2.8)

We have a homeomorphism $U_\epsilon \xrightarrow{\exp} V_\epsilon$ for each such ϵ .

~~BB~~ This lives within $\mathfrak{gl}(n) \rightarrow GL(n)$.

Proved it by defining \log via power series, and proving this is a ets., convergent inverse.

What's new. True for any matrix Lie group G .

Don't have to work with all of $GL(n)$ to get this.

Lemma. Suppose $\{B_m\} \in G$, a sequence converging to i .

Write $Y_m = \log B_m$. (know defined for $m \gg 0$
wlog defined for all m)

Suppose $Y_m \neq 0$ for all m , $\frac{Y_m}{\|Y_m\|} \rightarrow Y \in M_n(\mathbb{C})$.

Then $Y \in \mathfrak{g}$.

11.6

Proof. For any $t \in \mathbb{R}$, choose integers k_m s.t.

$k_m \|Y_m\| \rightarrow t$. Can do this because $\|Y_m\| \rightarrow 0$
and none of the Y_m are zero.

$$\text{So } e^{k_m Y_m} = \exp\left(k_m \|Y_m\| \cdot \frac{Y_m}{\|Y_m\|}\right) \rightarrow e^{+Y}$$

$$\text{But } e^{k_m Y_m} = (e^{Y_m})^{k_m} = B_m^{k_m} \in G.$$

Moral. $e^{+Y} \in G$. So $Y \in \mathfrak{g}$. Done

Proof of theorem. Regard $M_n(\mathbb{C}) = \mathbb{R}^{2n^2}$

Write $D :=$ ortho complement of \mathfrak{g} .

$$\begin{array}{ccc} \text{Define a map } \Phi : M_n(\mathbb{C}) & \longrightarrow & M_n(\mathbb{C}) \\ z & \longrightarrow & e^X e^Y \end{array}$$

where we always write $z = \begin{array}{cc} X & Y \\ \uparrow & \uparrow \\ \mathfrak{g} & D \end{array}$.

This is cts. and $\frac{d}{dt} \Phi(tX, 0) \Big|_{t=0} = X$

$$\frac{d}{dt} \Phi(0, tY) \Big|_{t=0} = Y.$$

So the derivative of Φ at $0 \in \mathbb{R}^{2n^2}$ is the identity which is invertible.

11.7

Inverse function theorem $\Rightarrow \mathbb{F}$ has a cts. local inverse
(defined in a nbd of I)

WTS, if $A \in V_\epsilon \cap G \Rightarrow \log A \in \mathfrak{g}$.

If not, there would be a sequence $A_m \in G \rightarrow I$
with $\log A_m \notin \mathfrak{g}$ for all m .

Write $A_m = e^{X_m} e^{Y_m}$ ($X_m \in \mathfrak{g}$, $Y_m \in D$)
 $X_m \rightarrow 0$, $Y_m \rightarrow 0$.

which we can do because \mathbb{F} has a local inverse.

We have $Y_m \neq 0$ because $e^{\mathfrak{g}} \in G$.

Since A_m and e^{X_m} are in G , so is e^{Y_m} .

Now, choose a subseq. of the Y_m (wlog assume it's the whole sequence)

with $\frac{Y_m}{\|Y_m\|} \rightarrow Y \in D$.
(Here $\|Y\| = 1$)

Why can we do this? $\frac{Y_m}{\|Y_m\|}$ is a unit vector

set of all such is compact
can find a subseq converging to something
and by construction it's in D .

By lemma, $Y \in \mathfrak{g}$. But $Y \in D = \mathfrak{g}^\perp$, contradiction. \blacksquare

12.1 (Review the big theorem)

Cor. G matrix Lie gr w/ Lie alg. \mathfrak{g} .

There exist nbds $U \ni 0$ in \mathfrak{g} , $V \ni I$ in G s.t. \exp is a homeomorphism $U \rightarrow V$.

Proof. Given ε as in Thm, let $U = U_\varepsilon \wedge \mathfrak{g}$
 $V = V_\varepsilon \wedge G$.

Then ~~onto~~ ^{one-to-one} and continuous by general theory.
Onto by theorem.

Cor. Let $k = \dim \mathfrak{g}$. (as an \mathbb{R} -vector space)

Then G is a smooth embedded ^{sub} manifold of $M_n(\mathbb{C})$ of dimension k . (So it's a Lie group.)

Corollary of Corollary. Locally path connected (\mathbb{R}^k is) so path conu \iff conu'd.

Proof involves a lot of topology terminology.

Idea. Have a homeomorphism $U \longrightarrow V$

choose an ε -box in U .

Get a nbd homeomorphic to \mathbb{R}^k in U , hence in V .

But the map $V \rightarrow gV$
 $x \rightarrow gx$ is a homeomorphism for every $g \in G$.

12.2. Cor. (G, \mathfrak{g}) as before.

Then $X \in \mathfrak{g} \iff \exists$ a smooth curve γ in $M_n(\mathbb{C})$,
 $\gamma(t) \in G$ for all t ,
 $\gamma(0) = I$,
 $\left. \frac{d\gamma}{dt} \right|_{t=0} = X$.

In other words: \mathfrak{g} is the tangent space at the identity to G .

Proof. \Rightarrow : Choose $\gamma(t) = e^{tX}$.

\Leftarrow : Given such a γ , for small t write

$\gamma(t) = e^{\delta(t)}$ with δ a smooth curve in \mathfrak{g} .

Now

$$\gamma'(0) = \left. \frac{d}{dt} e^{\delta(t)} \right|_{t=0} = \frac{d}{dt} e^{t\delta'(0)}$$

$$= e^{\delta(t)} \cdot \delta'(t) \Big|_{t=0} = e^0 \delta'(0) = \delta'(0).$$

And so $\delta'(0) = \gamma'(0)$ belongs to \mathfrak{g} .

Cor. If G is a commutative Lie group, every elt. of A can be written ~~as~~ in the form

$$A = e^{X_1} e^{X_2} \cdots e^{X_n}$$

for some $X_i \in \mathfrak{g}$.

12.3

Proof. (Not the book's, please check for ~~errors~~ mistakes!)
symmetrical small

Let U be a small nbd of $0 \in \mathfrak{g}$. Then e^U is open $\subseteq G$.

Consider everything that can be written

$$e^{X_1} \dots e^{X_n} \text{ with all the } X_i \in U.$$

It's a subgroup of G .

It is open ("obviously")

All of its cosets are open, hence it's also closed
connected \Rightarrow whole thing!

Cor. Given $G \xrightarrow[\Phi_2]{\Phi_1} H$ two homs of Lie groups

with assoc. homs $\mathfrak{g} \xrightarrow[\phi_2]{\phi_1} \mathfrak{h}$. If $\phi_1 = \phi_2$, $\Phi_1 = \Phi_2$.

Proof. $\Phi_1(e^{X_1} \dots e^{X_m}) = e^{\phi_1(X_1)} \dots e^{\phi_1(X_m)}$
 $= \Phi_2(e^{X_1} \dots e^{X_m})$

and this is everything.

Cor. If $G \xrightarrow{\Phi} H$ is a cts. homomorphism, it is smooth.

Proof. write ~~any~~ ~~any~~ a nbd. of arbitrary $g \in G$
as $\{ge^X : X \in \mathfrak{g}\}$.

Then if $h \in ge^X$, $\Phi(h) = \Phi(g) \Phi(e^X) = \Phi(g) e^{\phi(X)}$

So that Φ in this neighborhood is the composition of:

a linear map,
exponential map.

left mul by $\Phi(g)$. All are smooth

12.4

Cor. If G is a conn. matrix Lie group and \mathfrak{g} is abelian, then so is G .

Proof. Write any $A \in G$ as $e^{X_1} \dots e^{X_m}$ where all the X_i commute.

Cor. If $G \subseteq M_n(\mathbb{C})$ matrix Lie group, its identity component G_0 is a closed subgroup of $GL_n(\mathbb{C})$ and also a matrix Lie group.

It has the same Lie algebra as G .

Proof. Know it's a subgroup.

Open, and so are its cosets, so closed.

Lie algebras are the same, because the condition

$$\{e^{tX} \in G \text{ for all } t \in \mathbb{R}\}$$

if it is true, lies in G_0 since it is a smooth path.

13.1

My favorite representation.

$$V = \{\text{binary cubic forms}\}$$

$$= \{x_1 u^3 + x_2 u^2 v + x_3 u v^2 + x_4 v^3\}.$$

(Can talk about $V(\mathbb{C}), V(\mathbb{R})$ etc.)

$G = GL(2)$, V is a repⁿ by means of

$$(g \circ f)(u, v) = f((u, v)g).$$

So writing $\rho: GL(2) \rightarrow GL(4)$ for this repⁿ, get

$$\rho\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}\right) = \begin{pmatrix} a^3 & a^2 b & a b^2 & b^3 \\ 3a^2 c & a^2 d + 2abc & 2abd + bc^2 & 3b^2 d \\ 3ac^2 & 2acd + bc^2 & ad^2 + 2bcd & 3bd^2 \\ c^3 & c^2 d & cd^2 & d^3 \end{pmatrix}$$

Is it faithful? If $\rho\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}\right) = I_4$, $b = c = 0$, looks like

$$\begin{pmatrix} a^3 & 0 & 0 & 0 \\ 0 & a^2 d & 0 & 0 \\ 0 & 0 & ad^2 & 0 \\ 0 & 0 & 0 & d^3 \end{pmatrix}$$

So $a = d \in \mu_3$.

(Interesting question. Compute isotropy subgroups.)

13.2

Now compute the infinitesimal rep'n dp.

What is this?

time $\left(\begin{matrix} 1+a & \beta \\ \gamma & 1+\delta \end{matrix} \right) \circ f$

$\alpha, \beta, \gamma, \delta \rightarrow 0$

To compute in practice

Compute $\left(\begin{matrix} 1+a & \beta \\ \gamma & 1+\delta \end{matrix} \right) \circ f - f$, and throw out second powers of Greek letters:

$$\begin{pmatrix} (1+a)^3 - 1 & (1+a)^2 \beta & (1+a) \beta^2 & \beta^3 \\ 3(1+a)^2 \gamma & (1+a)^2 \delta(1+\delta) + 2(1+a) \beta \gamma - \beta^2 & 2a(1+a) \beta(1+\delta) + \beta \gamma^2 & 3\beta^2(1+\delta) \\ 3(1+a) \gamma^2 & 2(1+a) \gamma(1+\delta) + \beta \gamma^2 & (1+a)(1+\delta)^2 + 2\beta \gamma(1+\delta) - 1 & 3\beta(1+\delta)^2 \\ \gamma^3 & \gamma^2(1+\delta) & \gamma(1+\delta)^2 & (1+\delta)^3 - 1 \end{pmatrix}$$

↓ Throw away second powers

$$\begin{pmatrix} 3a & \beta & 0 & 0 \\ 3\gamma & 2a+\delta & 2\beta & 0 \\ 0 & 2\gamma & a+2\delta & 3\beta \\ 0 & 0 & \gamma & 3\delta \end{pmatrix}$$

You see why this is powerful. We've lost all the nonlinearity.

This is exactly the representation $gl(2) \rightarrow gl(4)$.

13.3

Now, compute $dp\left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}\right)\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 3x_1 \\ 2x_2 \\ x_3 \\ 0 \end{pmatrix}$.

This is how a small change in g affects gv .

Similarly $dp\left(\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}\right)\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} x_2 \\ 2x_3 \\ 3x_4 \\ 0 \end{pmatrix}$

and with the other two we also get

$$\left(\begin{array}{c|c|c|c} 3x_1 & x_2 & 0 & 0 \\ 2x_2 & 2x_3 & 3x_2 & x_2 \\ x_3 & 3x_4 & 2x_3 & 2x_3 \\ 0 & 0 & x_4 & 3x_4 \end{array} \right) 1$$

a matrix whose ~~disc~~ determinant is

$$3(x_2^2 x_3^2 + 18x_1 x_2 x_3 x_4 - 4x_1 x_3^3 - 4x_2^3 x_4 - 27x_1^2 x_4^2) \\ = 3 \text{Disc}(f).$$

~~In other words, the Lie algebra action is injective iff \mathfrak{g} is nontrivial.~~

The point is, $G\vec{x}$ is 4-dimensional (depends on \vec{x})
 \iff a small neighborhood is \uparrow around $1 \in G$
 ~~$\iff G\vec{x}$ is~~ $\iff g\vec{x}$ is.

~~Case~~ So see what the four ~~base~~ basis elts. of \mathfrak{g} do to a generic vector.

12.5 (Review: 13.4)

Basic representation theory.

If G is a matrix Lie group, a (finite dim. cpx) representation of G is a Lie group homomorphism

$$\Pi : G \rightarrow GL(V),$$

where V is a f.d. cpx vector space.

Same with reals.

Similarly, if \mathfrak{g} is a (real/cpx) Lie algebra, a rep'n is a Lie alg hom

$$\pi : \mathfrak{g} \rightarrow \mathfrak{gl}(V).$$

If Π/π is 1-1, call it faithful.

Often write $g \cdot v$ instead of $\Pi(g)v$.

(Representations equivalent to ^{linear acts} group actions on vector spaces).

Example. (Do at board)

$GL(2)$ acting on binary cubic forms, via

$$g \circ f(u, v) = f((u, v)g).$$

12.6 = 13.5

Def. Let (π, V) be a f.d. rep of a matrix Lie gp G .
A subspace W is invariant if $\pi(A)w \in W$ for $w \in W$
 $A \in G$.

(nontrivial) if not W or 0)

A rep'n is irreducible if it has no nontrivial invariant subspaces.

Analogously for Lie algebra rep's.

Def. Given rep's (π, V) and (Σ, W) of a matrix Lie group G .

A map $\phi: V \rightarrow W$ is an intertwining map of rep's if

$$(*) \quad \phi(\pi(A)v) = \Sigma(A)\phi(v)$$

for all $A \in G, v \in V$.

Sim: rep'n of a Lie algebra.

If ϕ is an isomorphism also, we say it is an isomorphism
of representations.

Problem. Classify all rep's of a Lie group up to iso!

Note, for $(*)$, can also write

$$\phi(A \cdot v) = A \cdot \phi(v).$$

So ϕ commutes with "the" action of A .

Caution: There are two different actions!

12.7 = 13.6 = 14.1
→ (same as before!!)

Prop. Given G, \mathfrak{g} , a f.d. rep'n $\Pi: G \rightarrow GL(V)$.

Then \exists a unique rep'n of \mathfrak{g} acting on V with

$$\Pi(e^X) = e^{\pi(X)}$$

$$\pi(X) = \left. \frac{d}{dt} \Pi(e^{tX}) \right|_{t=0}$$

$$\pi(AXA^{-1}) = \Pi(A)\pi(X)\Pi(A)^{-1}$$

Proposition. (4.5)

(1) Let G be a conn'd Lie gp with Lie alg \mathfrak{g} .

Π a rep'n of G with π the assoc rep'n of \mathfrak{g} .

Then Π is irreducible $\iff \pi$ is.

(2) Again let G be a conn'd Lie group, Π_1, Π_2 rep'ns of it, π_1, π_2 associated Lie algebra rep'ns.

Then π_1 and π_2 are iso if and only if Π_1, Π_2 are.

This is nice.

(2) says: If π comes from a Lie group rep'n, then it's determined up to isomorphic.

Thm 5.6 (later). If G is simply connected, then π must come from a Lie group homomorphism (which is uniquely determined!)

13.7 = 14.2

Moral. If we ^{want to} understand the rep'n theory of simply connected Lie gps, just understand their Lie algebras.

Proof. (2) is an exercise! Prove (1).

Suppose first π irreducible. Show π is.

Let $W \subseteq V$ be an invariant subspace.

Since G is conn'd, can write any $A \in G$ as

$$A = e^{X_1} e^{X_2} \dots e^{X_m} \quad (X_i \in \mathfrak{g})$$

Now W is invariant under all the $\pi(X_j)$.

Hence also each

$$\exp(\pi(X_j)) = I + \pi(X_j) + \frac{\pi(X_j)^2}{2} + \dots$$

hence under

$$\begin{aligned} \pi(A) &= \pi(e^{X_1} \dots e^{X_m}) = \pi(e^{X_1}) \dots \pi(e^{X_m}) \\ &= e^{\pi(X_1)} \dots e^{\pi(X_m)} \end{aligned}$$

So W is invariant under $\pi(G)$ in addition to $\pi(\mathfrak{g})$.

So it's $\{0\}$ or V .

$$\underline{13.8} = 14.3$$

Conversely, suppose π irreducible, W invariant for π . Then W is invariant under every vector of the form $\pi(\exp tX)$ for $X \in \mathfrak{g}$,

$$\text{hence under } \pi(X) = \left. \frac{d}{dt} \pi(e^{tX}) \right|_{t=0}.$$

Since π irred. W is $\{0\}$ or V .

Examples.

The standard representation.

A matrix Lie group $G \subseteq GL(n, \mathbb{C})$.

Just take the inclusion $G \hookrightarrow GL(n, \mathbb{C})$.

Similarly if $\mathfrak{g} \subseteq M_n(\mathbb{C})$. Just take the identity map.

The trivial representation.

$$\pi: G \rightarrow GL(\mathbb{C})$$

$$\pi(A) = I \quad \forall A.$$

$$\pi: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathbb{C})$$

$$\pi(A) = 0.$$

Both irreducible

The adjoint representation.

$$\text{Ad}: G \rightarrow GL(\mathfrak{g})$$

$$A \rightarrow \text{Ad}_A = \{ X \rightarrow A X A^{-1} \}$$

$$\text{ad}: \mathfrak{g} \rightarrow GL(\mathfrak{g})$$

$$A \rightarrow \text{ad}_A = \{ X \rightarrow [A, X] = AX - XA \}$$

$$13.9 = 14.4$$

Let $V_m = \{ \text{homo polys of degree } m \text{ in two (cpx) vars} \}$

$$f(z_1, z_2) = a_0 z_1^m + a_1 z_1^{m-1} z_2 + \dots + a_m z_2^m.$$

$$(\dim V_m = m+1)$$

One rep'n ^{of $\mathfrak{sl}(2)$ or $\mathfrak{su}(2)$} ~~of $\mathfrak{sl}(2)$~~ we can get is

$$(\pi_m(U) f)(z) = f(U^{-1} z).$$

Alternatively,

$$(\pi_m(U) f)(z) = f(U^T z).$$

We have, with the first,

$$\begin{aligned} \pi_m(U_1) (\pi_m(U_2) f)(z) &= (\pi_m(U_2) f)(U_1^{-1} z) \\ &= (U_2^{-1} U_1^{-1} z) \\ &= ((U_1, U_2)^{-1} z) \end{aligned}$$

$$= (\pi_m(U_1, U_2) f)(z).$$

Same if you put transposes.

Later: (1) These are irreducible;

(2) every f.d. rep'n of $\mathfrak{sl}(2)$ is iso to one of these.

14.5

How to compute the associated rep'n π_m of $\mathfrak{sl}(2)$?

$$\rightarrow (\pi_m(X)f)(z) = f(e^{-tX}z) \Big|_{t=0}.$$

Make sure you understand why the parens are where they are!!

Write $z(t) = (z_1(t), z_2(t))$ be the curve in \mathbb{C}^2 $z(t) = e^{-tX}z$.

We have

$$\pi_m(X)f = \left(\frac{\partial f}{\partial z_1} \frac{dz_1}{dt} + \frac{\partial f}{\partial z_2} \frac{dz_2}{dt} \right) \Big|_{t=0}$$

$$\text{Now, } \frac{dz}{dt} \Big|_{t=0} = -Xz$$

So above is

$$-\frac{\partial f}{\partial z_1} (X_{11}z_1 + X_{12}z_2) - \frac{\partial f}{\partial z_2} (X_{21}z_1 + X_{22}z_2)$$

Choose the following basis for $\mathfrak{sl}(2)$:

$$H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad X = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad Y = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$\pi_m(H) = -z_1 \frac{\partial}{\partial z_1} + z_2 \frac{\partial}{\partial z_2}.$$

$$\pi_m(X) = -z_2 \frac{\partial}{\partial z_1}$$

$$\pi_m(Y) = -z_1 \frac{\partial}{\partial z_2}$$

These are endomorphisms of V_m .

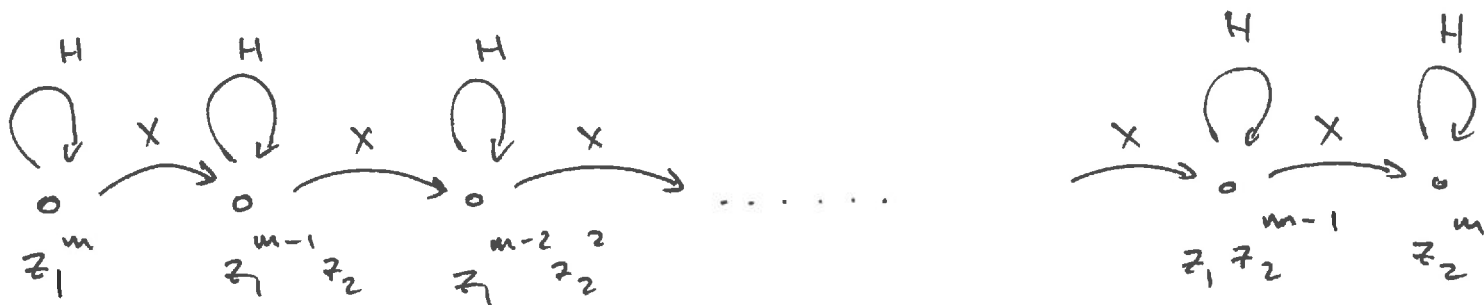
14.6

What do these do to a basis elt. $z_1^{m-k} z_2^k$ for V_m ?

$$\pi_m(H)(z_1^{m-k} z_2^k) = (-m + 2k) z_1^{m-k} z_2^k$$

$$\pi_m(X)(z_1^{m-k} z_2^k) = -(m-k) z_1^{m-k-1} z_2^{k+1}$$

$$\pi_m(Y)(z_1^{m-k} z_2^k) = -k z_1^{m-k+1} z_2^{k-1}$$



All of them are eigenvectors for $\pi_m(H)$ w/ eigenvalue $-m + 2k$.

(zero only if $m = 2k$, so $z_1^{m/2} z_2^{m/2}$ w/ m even.)

$\pi_m(X)$ shifts you to the right one. (adds 1 to k)

If you're already at the right, $m = k$ and $\pi_m(X)$ acts by 0.

$\pi_m(Y)$ shifts you to the left one.

If you're already at the left, $k = 0$ and $\pi_m(Y)$ acts by 0.

Also: $\pi_m(X)$ increases eigenvalue of $\pi_m(H)$ by 2

$\pi_m(Y)$ decreases eigenvalue of $\pi_m(H)$ by 2.

14.7

Proposition. The representation Π of $SL(2)$ is irreducible.

Proof. It suffices to show the representation π of $sl(2)$ is irreducible.

But now you can play games with the diagram. (See Hall, p. 84 for a more formal proof.)

Suppose W is an invariant subspace and $0 \neq w \in W$. Hit it with $\pi_m(X)$ a bunch of times until you get a nonzero multiple of e_2^w . That's in W .

Now keep marching to the left.

(15.1 =)

In the book:

Direct sums. If G acts on V_1, V_2 it acts on $V_1 \oplus V_2$ by each component.

Same with \mathfrak{g} .

Tensor products. pp 85 \rightarrow Review of construction.

Two constructions.

- (1) Given a rep'n (π_1, U) of G
- (π_2, V) of H

Get a rep'n $(\pi_1 \otimes \pi_2, U \otimes V)$ of $G \times H$

$$(\pi_1 \otimes \pi_2)(A, B) = \pi_1(A) \otimes \pi_2(B)$$

for $A \in G$ and $B \in H$.

- (2) If both are rep'n of G

$$(\pi_1 \otimes \pi_2)(A) = \pi_1(A) \otimes \pi_2(A).$$

15.2

Proposition. Given rep's π_1 of \mathfrak{g} , π_2 of \mathfrak{h}
 $\pi_1 \otimes \pi_2$ of $\mathfrak{g} \times \mathfrak{h}$.

If $\pi_1 \otimes \pi_2$ is the associated rep'n of $\mathfrak{g} \oplus \mathfrak{h}$, then

$$(\pi_1 \otimes \pi_2)(X, Y) = \pi_1(X) \otimes I + I \otimes \pi_2(Y),$$

for all $X \in \mathfrak{g}, Y \in \mathfrak{h}$.

Proof. If $u(t)$ smooth curve in U , $v(t)$ in V , the product rule reads

$$\frac{d}{dt}(u(t) \otimes v(t)) = \frac{du}{dt} \otimes v(t) + u(t) \otimes \frac{dv}{dt}$$

and so

$$(\pi_1 \otimes \pi_2)(X, Y)(u \otimes v)$$

$$= \left. \frac{d}{dt} \pi_1(e^{tX}) u \otimes \pi_2(e^{tY}) v \right|_{t=0}$$

$$= \left(\left. \frac{d}{dt} \pi_1(e^{tX}) u \right|_{t=0} \right) \otimes v + u \otimes \left(\left. \frac{d}{dt} \pi_2(e^{tY}) v \right|_{t=0} \right).$$

In general, given rep's (π_1, U) of \mathfrak{g} and (π_2, V) of \mathfrak{h} ,
get a rep'n $\pi_1 \otimes \pi_2$ of $\mathfrak{g} \oplus \mathfrak{h}$ on $U \otimes V$:

$$(\pi_1 \otimes \pi_2)(X, Y) = \pi_1(X) \otimes I + I \otimes \pi_2(Y).$$

This is linear in (X, Y) .

$\pi_1(X) \otimes \pi_2(Y)$ is not!

15.3

Dual representations.

whatever field V is defined over

Given V , let $V^* = \text{Hom}(V, k)$ be its dual space.
(linear fnc. from V to k)

Given $A \in GL(V)$, define $A^T \in GL(V^*)$ by

$$(A^T \phi)(v) = \phi(Av) \quad \text{for each } \phi \in V^*, v \in V.$$

If v_1, \dots, v_n is a basis, define the dual basis ϕ_1, \dots, ϕ_n by $\phi_j(v_k) = \delta_{jk}$

so that you get an isomorphism $V \longrightarrow V^*$
 $v_i \longmapsto \phi_i.$

(Warning. This assumes V is finite dimensional.
Weird shit happens otherwise.)

Exercise. The matrix A^T is the usual matrix transpose of A .

Claim. $(AB)^T = B^T A^T.$

Crap Proof. Write it out using matrix coefficients.
(Please DON'T actually do this)

Better proof. For all ϕ and v ,

$$((AB)^T \phi)(v) = \phi(ABv)$$

$$(B^T(A^T \phi))(v) = (A^T \phi)(Bv) = \phi(ABv).$$

Def. Given a rep'n (π, V) of G , the dual (contragredient) rep'n is the rep. (π^*, V^*) on the dual space given by

$$\pi^*(g) = (\pi(g^{-1}))^T.$$

Note that inverses and transposes both flip order, so we've straightened out here.

15.4

Check, we get the assoc. rep'n $\pi^*(X) = -\pi(X)^T$.

Proposition/Exercise. Given (π, \mathfrak{g}) , π^* irred $\iff \pi$ irred,

$$(\pi^*)^* \cong \pi.$$

Similarly for Lie alg. rep'ns.

Complete reducibility.

Def. A f.d. rep'n of a group or Lie algebra is completely reducible if it is iso to a direct sum of finitely many irreducible rep'ns.

(So, in particular, irreducible rep'ns are completely reducible.
Yeah, I know.)

We can understand the irred. rep'ns, so if all rep'ns of a given Lie group are CR then this is really nice.

This happens if the Lie group is "reductive".

Ex. Given $\pi: \mathbb{R} \rightarrow GL(2, \mathbb{C})$

$$x \rightarrow \begin{pmatrix} 1 & x \\ 0 & 1 \end{pmatrix}.$$

This is not completely reducible.

Can check, The invariant subspaces are $\{0\}$, $\text{span}(v_1)$, and V .

15.5 = 16.1

Proposition. Let V be a c.r. rep'n of a group or Lie algebra. Then

- (1) For every invariant $U \subseteq V$ there is an invariant complement W with $V = U \oplus W$.
- (2) Every invariant subspace of V is CR.

Proof. (1) Write $V = U_1 \oplus \dots \oplus U_k$ irred. invariant.
Given $U \neq V$, there is some $U_{j_1} \not\subseteq U$, and so with $U_{j_1} \cap U = \{0\}$.

Either $U_{j_1} + U = V$, sum is direct, and we're done, or $U_{j_1} + U$ doesn't contain some U_{j_2} . Etc. Keep going.

(2) If $U \subseteq V$ invariant, first establish ~~existence of~~ complement property of (1) for U .

Suppose $X \subseteq U$ invariant.

By (1), can write $V = X \oplus Y$, Y also invariant

Write $Z := Y \cap U$ invariant and show $U = X \oplus Z$.

Write any $u \in U$ as $u = x + y$ ($x \in X, y \in Y$)
but $y = u - x \in U - U = U$
so $y \in Z$ done.

So, finally, if U is not already irreducible,

find some invariant subspace X with $U = X \oplus Z$
 X, Z invariant

If these are not irreducible, decompose further
Eventually we win.

15.6

Prop. If G mat Lie gp, (π, V) a f.d. unitary rep'n of G ,
then π is completely reducible.

similarly, real
If \mathfrak{g} is a Lie algebra and π is f.d. "unitary" ($\pi(X)^* = -\pi(X)$)
then π is completely reducible.

What does unitary mean? That $\pi(g) \in U(V)$ for all g .

Proof. Let $w \in W$ be invariant and write $V = W \oplus W^\perp$
orthogonal complement wrt the inner product

Now by unitariness, $\pi(A)^* = \pi(A)^{-1} = \pi(A^{-1})$ for $A \in G$

So for all $w \in W, v \in W^\perp$,

$$\begin{aligned}\langle \pi(A)v, w \rangle &= \langle v, \pi(A)^* w \rangle = \langle v, \pi(A^{-1})w \rangle \\ &= \langle v, \text{smth in } W \rangle \\ &= 0.\end{aligned}$$

So W^\perp must also be invariant.

Now apply the same trick.

$$V = W \oplus W^\perp$$

If either is not irreducible, find an invariant subspace
and break up in the same way.
Eventually this stops.

(Argument for π : similar.)

Theorem. If G is a compact matrix Lie group, every f.d.
rep'n is completely reducible

Proof. Cook up a weird inner product with respect to
which it's unitary. See pp. 92-94.

15.7

Schur's lemma.

(1) Let V, W irred (real or cpx) rep's of a group or Lie algebra, and $\phi: V \rightarrow W$ an intertwining map.

Then ϕ is 0 or an iso.

(2) Given V complex, and $\phi: V \rightarrow V$, then $\phi = \lambda I$ for some $\lambda \in \mathbb{C}$.

(3) Given V, W cpx as above with ϕ_1, ϕ_2 nonzero intertwining maps $V \rightarrow W$. Then $\phi_1 = \lambda \phi_2$ for some $\lambda \in \mathbb{C}$.

Cor. #1. Let π be a complex irred ^{irreducible representation} of a mot. Lie gp G . If $A \in Z(G)$ (the center) then $\pi(A) = \lambda I$ for some $\lambda \in \mathbb{C}$.

Similarly if π is a cpx irrep of \mathfrak{g} with $A \in Z(\mathfrak{g})$, then $\pi(A) = \lambda I$.

Proof. (for group case; Lie algebra case similar)

Since $\pi(A)\pi(B) = \pi(B)\pi(A)$, $\pi(A)$ is an intertwining map of the space with itself!

Cor. #2. A complex irrep of a commutative group or Lie algebra must be one-dimensional.

Proof. Since $\pi(A) = \lambda A$ for each A , every subspace of V is invariant.

15.8

Proof of Schur (Group case).

(1) Let $v \in \ker(\phi)$. Then

$$\phi(\pi(A)v) = \Sigma(A)\phi(v) = 0.$$

So $\ker \phi$ is invariant. DONE

Well, almost: it's zero or one-to-one

and in the latter case $\text{Im}(\phi)$ is invariant.

For all $w = \phi(v)$,

$$\Sigma(A)w = \Sigma(A)\phi(v) = \phi(\pi(A)v).$$

(2) Given $\phi: V \rightarrow V$ with $\phi\pi(A) = \pi(A)\phi$.

Now ϕ has an eigenvalue $\lambda \in \mathbb{C}$ w/ eigenspace U .

So U is an invariant subspace, hence $U = V$.

(3) $\phi_1 \circ \phi_2^{-1}$ intertwining map $V \rightarrow V$. Use (2).

All reps of $\mathfrak{sl}(2, \mathbb{C})$:

$$X = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad Y = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$[H, X] = 2X, \quad [H, Y] = -2Y, \quad [X, Y] = H.$$

So the matrix of $\text{ad}(H)$ is $\begin{bmatrix} 0 & \\ & 2 \\ & & -2 \end{bmatrix}$.

We already had the representations of binary n -ic forms discussed before.

Departing from Hall, write

$$\underline{\text{Sym}}^n(\mathbb{C}^2) = \{ \text{binary cubic forms of deg } n \}.$$

15.9

Then, for each $n \geq 1$, $\text{Sym}^n(\mathbb{C}^2)$ is an irrep of dim $n+1$.

Theorem. Every irrep of $\mathfrak{sl}(2, \mathbb{C})$ is one of these.

Proof. Given an irrep $(\pi, V) \dots$

Lemma. Let u be an eigenvector of $\pi(H)$ with EV $\varphi \in \mathbb{C}$.

Then

$$\pi(H)\pi(X)u = (\varphi + 2)\pi(X)u.$$

Proof.
$$\begin{aligned}\pi(H)\pi(X)u &= \pi(X)\pi(H)u + [\pi(H), \pi(X)]u \\ &= \pi(X)\pi(H)u + \pi([H, X])u \\ &= \cancel{\pi(X)\pi(H)u} \\ &= \pi(X) \cdot \varphi u + 2\pi(X)u.\end{aligned}$$

So: $\pi(X)$ sends eigenvectors to eigenvectors, and raises the EV by 2.

Similarly,
$$\pi(H)\pi(Y)u = (\varphi - 2)\pi(Y)u.$$

Proof of theorem. Given an irrep (π, V) of $\mathfrak{sl}(2, \mathbb{C})$.

Let u be an eigenvector for $\pi(H)$ (it must have one!) with eigenvalue φ .

Then by lemma,
$$\pi(H)\pi(X)^k u = (\varphi + 2k)\pi(X)^k u.$$

We can't have infinitely many eigenvalues!

So, for some $N \geq 0$,

$$u_0 := \pi(X)^N u \neq 0, \quad \pi(X)^{N+1} u = 0.$$

Write $\lambda = \varphi + 2N$,

$$\pi(H)u_0 = \lambda u_0 \quad \pi(X)u_0 = 0.$$

15.10 = 16. ~~10~~ b for each k

Write now $u_k = \pi(Y)^k u_0$, with $\pi(H)u_k = (\lambda - 2k)u_k$

Can check: $\pi(X)u_k = k(\lambda - (k-1))u_{k-1}$ for all $k \geq 1$.

Let u_m be the last nonzero one. (Same argument as before)

Now $0 = u_{m+1} = \pi(X)u_{m+1} = (m+1)(\lambda - m)u_m$ so $\lambda = m$.

We have thus listed basis vectors for an invariant subspace of V
(by irreducibility, is V itself)

Have to be linearly independent since they are EV's of $\pi(H)$ with distinct eigenvalues.

But we've just written down the entire representation.

Conversely, check that we really do have a representation.

Use our earlier construction, or define $\pi(H)$, $\pi(X)$, $\pi(Y)$ by the relations above and check the commutators.

16.8

$$\textcircled{E} x^2 \rightarrow (ax + cy) \cdot x + x \cdot (ax + cy) \\ = 2x(ax + cy)$$

$$xy \rightarrow (ax + cy) \cdot y + \cancel{(bx + dy)} x \cdot (bx + dy)$$

This is all a bit weird.

So ask, what does $H = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ do?

Or, more precisely, $\pi(H)$

$$H(x \cdot x) = x \cdot H(x) + H(x) \cdot x = 2x^2$$

$$H(x \cdot y) = x \cdot H(y) + H(x) \cdot y = xy - xy = 0$$

$$H(y \cdot y) = y \cdot H(y) + H(y) \cdot y = -2y^2$$

Similarly, $X = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ sends $y \rightarrow x$ and kills x .

$$\textcircled{A} X(x \cdot x) = x \cdot X(x) + X(x) \cdot x = 0$$

$$X(x \cdot y) = x \cdot X(y) + X(x) \cdot y = x^2$$

$$X(y^2) = y \cdot X(y) + X(y) \cdot y = 2xy$$

Similarly with $Y = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$.

natural basis

So the point is these are all eigenvectors

$$\text{EV } \begin{Bmatrix} x^2, & xy, & y^2 \end{Bmatrix}$$

$$\begin{matrix} 2 & 0 & -2 \end{matrix}$$

(x-exponent) - (y-exponent)

$$\text{Sym}^3 V = \text{Span} \left\{ \begin{matrix} x^3, & x^2y, & xy^2, & y^3 \end{matrix} \right\}$$

$$\begin{matrix} 3 & 1 & -1 & -3 \end{matrix}$$

16.9

$$\text{Sym}^4 V = \text{Span} \left\{ \begin{matrix} x^4 & x^3 y & x^2 y^2 & x y^3 & y^4 \\ 4 & 2 & 0 & -2 & 4 \end{matrix} \right\}$$

What about $\text{Sym}^2(\text{Sym}^2 V)$?

If the 3 basis vectors of $\text{Sym}^2 V$ are v_1, v_2, v_3 then this is spanned by $\left\{ \begin{matrix} v_1 v_2, v_1 v_3, \text{ and } v_2 v_3 \\ v_1^2, v_2^2, v_3^2 \end{matrix} \right\}$.

So:

$$\text{Sym}^2(\text{Sym}^2 V) = \text{Span} \left\{ \begin{matrix} x^2 \cdot x^2, x^2 \cdot xy, x^2 \cdot y^2, \\ xy \cdot xy, xy \cdot y^2, y^3 \end{matrix} \right\}$$

It is 6-dimensional, and we get a natural surjection

$$\text{Sym}^2(\text{Sym}^2 V) \longrightarrow \text{Sym}^4 V$$

$$q_1 \cdot q_2 \longrightarrow q_1 q_2$$

whose kernel is spanned by $x^2 \cdot y^2 - xy \cdot xy$.
(Does your head hurt yet?)

Can we figure out the eigenvalues directly?

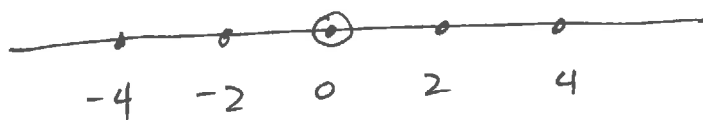
If v_1 and $v_2 \in \text{Sym}^2 V$ are EV's of H with EV λ_1, λ_2 ,

$$\begin{aligned} H(v_1 \cdot v_2) &= v_1 \cdot H(v_2) + H(v_1) \cdot v_2 \\ &= \lambda_2 v_1 \cdot v_2 + \lambda_1 v_1 \cdot v_2 \\ &= (\lambda_1 + \lambda_2) v_1 \cdot v_2. \end{aligned}$$

So: $-2 + -2, -2 + 0, -2 + 2,$
 $0 + 0, 0 + 2, 2 + 2.$

16.10

Eigenvalues of
 $\text{Sym}^2(\text{Sym}^2 V)$



• : multiplicity 1

⊙ : multiplicity

Now by general theory (unproved so far)

$\mathfrak{sl}(2)$ is simple (no ideals)

hence semisimple (direct sum of simples)

hence reductive.

So $\text{Sym}^2(\text{Sym}^2 V)$ is a direct sum of irreducibles,
and we know all irreducibles are $\text{Sym}^k V$
and can be read off from their eigenvalues.

$$\text{Here just } \text{Sym}^2(\text{Sym}^2 V) = \text{Sym}^4 V \oplus \underbrace{\text{Sym}^0 V}_{\text{Trivial rep}}$$

Ex. Verify this!